

Dynamic Panel Data Models

Exercises

1. Consider the simple dynamic model,

$$\begin{aligned} y_{it} &= \gamma y_{i,t-1} + \alpha_i^* + \varepsilon_{it}, \quad i = 1, \dots, N, \quad t = 1, \dots, T \\ \alpha_i^* &= \alpha + \alpha_i \end{aligned}$$

where $|\gamma| < 1$, y_{i0} is observable, $E(\varepsilon_{it}) = 0$, $E(\varepsilon_{it}\varepsilon_{jt}) = \sigma_\varepsilon^2$, if $i = j$ and $t = s$, and $E(\varepsilon_{it}\varepsilon_{jt}) = 0$ otherwise.

- a) Define the LSDV estimators of α_i and γ .
- b) Define the LSDV bias considering T fixed and $N \rightarrow \infty$.
- c) Indicate two alternative estimators which overcome the bias problem discussed in b).

Proposed Solutions:

1. a) Define the LSDV estimators of α_i and γ .

Solution: Note that

$$\begin{aligned} \hat{\alpha}_i &= \bar{y}_i - \hat{\gamma}_{LSDV} \bar{y}_{i,-1} \\ \hat{\gamma}_{LSDV} &= \left[\sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})^2 \right]^{-1} \left[\sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})(y_{i,t} - \bar{y}_i) \right] \end{aligned}$$

where $\bar{y}_i = \frac{1}{T} \sum_{t=1}^T y_{it}$ and $\bar{y}_{i,-1} = \frac{1}{T} \sum_{t=1}^T y_{i,t-1}$.

1. b) LSDV bias.

Solution: Note that

$$\hat{\gamma}_{LSDV} - \gamma = \left[\frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})^2 \right]^{-1} \left[\frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})(\varepsilon_{i,t} - \bar{\varepsilon}_i) \right]$$

Consider first the numerator

$$\frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})(\varepsilon_{i,t} - \bar{\varepsilon}_i)$$

and assume that T is fixed. Thus,

$$\begin{aligned}
& p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})(\varepsilon_{i,t} - \bar{\varepsilon}_i) \\
&= p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T y_{i,t-1} \varepsilon_{i,t} - p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \bar{y}_{i,-1} \varepsilon_{i,t} \\
&\quad - p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T y_{i,t-1} \bar{\varepsilon}_i + p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \bar{y}_{i,-1} \bar{\varepsilon}_i
\end{aligned} \tag{1}$$

By definition,

$$\begin{aligned}
p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T y_{i,t-1} \varepsilon_{i,t} &= E(y_{i,t-1} \varepsilon_{i,t}) = 0 \\
p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T y_{i,t-1} \bar{\varepsilon}_i &= p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \bar{\varepsilon}_i \sum_{t=1}^T y_{i,t-1} \\
&= p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \bar{\varepsilon}_i T \bar{y}_{i,-1} \\
&= p \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \bar{\varepsilon}_i \bar{y}_{i,-1}
\end{aligned}$$

Similarly,

$$\begin{aligned}
p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \bar{y}_{i,-1} \varepsilon_{i,t} &= p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \bar{y}_{i,-1} \sum_{t=1}^T \varepsilon_{i,t} \\
&= p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \bar{y}_{i,-1} T \bar{\varepsilon}_i \\
&= p \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \bar{y}_{i,-1} \bar{\varepsilon}_i \\
p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \bar{y}_{i,-1} \bar{\varepsilon}_i &= p \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \bar{y}_{i,-1} \bar{\varepsilon}_i
\end{aligned}$$

Thus, substituting these results into (1) we observe for the numerator of the LSDV that,

$$p \lim_{N \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T (y_{i,t-1} - \bar{y}_{i,-1})(\varepsilon_{i,t} - \bar{\varepsilon}_i) = -p \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \bar{y}_{i,-1} \bar{\varepsilon}_i.$$

Moreover, note that by recursive substitution y_{it} can be written as,

$$\begin{aligned} y_{it} &= \varepsilon_{it} + \gamma\varepsilon_{i,t-1} + \gamma^2\varepsilon_{i,t-2} + \dots + \gamma^{t-1}\varepsilon_{i1} \\ &\quad + \frac{1-\gamma^t}{1-\gamma}\alpha_i^* + \gamma^t y_{i0} \end{aligned}$$

Similarly, for $y_{i,t-1}$

$$\begin{aligned} y_{i,t-1} &= \varepsilon_{i,t-1} + \gamma\varepsilon_{i,t-2} + \gamma^2\varepsilon_{i,t-3} + \dots + \gamma^{t-2}\varepsilon_{i1} \\ &\quad + \frac{1-\gamma^{t-1}}{1-\gamma}\alpha_i^* + \gamma^{t-1}y_{i0} \end{aligned}$$

and so on for the other y_{ik} , $k = t-2, \dots, 1$.

Summing $y_{i,t-1}$ over t we establish that,

$$\begin{aligned} \sum_{t=1}^T y_{i,t-1} &= \varepsilon_{i,T-1} + \frac{1-\gamma^2}{1-\gamma}\varepsilon_{i,T-2} + \dots + \frac{1-\gamma^{T-1}}{1-\gamma}\varepsilon_{i1} \\ &\quad + \frac{(T-1)-\gamma T + \gamma^T}{(1-\gamma)^2}\alpha_i^* + \frac{1-\gamma^T}{1-\gamma}y_{i0} \end{aligned}$$

Note that $\sum_{t=1}^T y_{i,t-1} = T\bar{y}_{i,-1}$.

Hence,

$$\begin{aligned} p \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \bar{y}_{i,-1} \bar{\varepsilon}_i &= p \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \frac{1}{T} \left\{ \varepsilon_{i,T-1} + \frac{1-\gamma^2}{1-\gamma}\varepsilon_{i,T-2} + \dots + \frac{1-\gamma^{T-1}}{1-\gamma}\varepsilon_{i1} \right. \\ &\quad \left. + \frac{(T-1)-\gamma T + \gamma^T}{(1-\gamma)^2}\alpha_i^* + \frac{1-\gamma^T}{1-\gamma}y_{i0} \right\} \times \\ &\quad \times \left(\frac{1}{T}(\varepsilon_{i1} + \dots + \varepsilon_{iT}) \right) \end{aligned}$$

2. For $T = 2$ consider a standard unobserved effects model

$$y_{it} = \mathbf{x}_{it}\beta + c_i + u_{it}, \quad t = 1, 2$$

Let $\hat{\beta}_{FE}$ and $\hat{\beta}_{FD}$ denote the fixed effects and first difference estimators, respectively.

- a) Show that the FE and FD estimates are numerically identical.
- b) Show that the error variance estimates from the FE and FD methods are numerically identical.

2. **Solution: a)** Let

$$\begin{aligned}\bar{x}_i &= \frac{(x_{i1} + x_{i2})}{2} \\ \bar{y}_i &= \frac{(y_{i1} + y_{i2})}{2}\end{aligned}$$

and

$$\begin{aligned}\tilde{x}_{i1} &= x_{i1} - \bar{x}_i & \tilde{x}_{i2} &= x_{i2} - \bar{x}_i \\ \tilde{y}_{i1} &= y_{i1} - \bar{y}_i & \tilde{y}_{i2} &= y_{i2} - \bar{y}_i\end{aligned}$$

For T=2 the fixed estimator is,

$$\hat{\beta}_{FE} = \frac{\sum_{i=1}^N (\tilde{x}'_{i1} \tilde{y}_{i1} + \tilde{x}'_{i2} \tilde{y}_{i2})}{\sum_{i=1}^N (\tilde{x}'_{i1} \tilde{x}_{i1} + \tilde{x}'_{i2} \tilde{x}_{i2})}$$

Now by simple algebra

$$\begin{aligned}\tilde{x}_{i1} &= \frac{(x_{i1} - x_{i2})}{2} = -\frac{\Delta x_{i2}}{2} \\ \tilde{x}_{i2} &= \frac{(x_{i2} - x_{i1})}{2} = \frac{\Delta x_{i2}}{2} \\ \tilde{y}_{i1} &= \frac{(y_{i1} - y_{i2})}{2} = -\frac{\Delta y_{i2}}{2} \\ \tilde{y}_{i2} &= \frac{(y_{i2} - y_{i1})}{2} = \frac{\Delta y_{i2}}{2}\end{aligned}$$

Therefore,

$$\begin{aligned}(\tilde{x}'_{i1} \tilde{x}_{i1} + \tilde{x}'_{i2} \tilde{x}_{i2}) &= \frac{\Delta x'_{i2} \Delta x_{i2}}{4} + \frac{\Delta x'_{i2} \Delta x_{i2}}{4} \\ &= \frac{\Delta x'_{i2} \Delta x_{i2}}{2}\end{aligned}$$

and

$$\begin{aligned}(\tilde{x}'_{i1} \tilde{y}_{i1} + \tilde{x}'_{i2} \tilde{y}_{i2}) &= \frac{\Delta x'_{i2} \Delta y_{i2}}{4} + \frac{\Delta x'_{i2} \Delta y_{i2}}{4} \\ &= \frac{\Delta x'_{i2} \Delta y_{i2}}{2}\end{aligned}$$

Thus,

$$\begin{aligned}
\hat{\beta}_{FE} &= \frac{\sum_{i=1}^N (\tilde{x}'_{i1} \tilde{y}_{i1} + \tilde{x}'_{i2} \tilde{y}_{i2})}{\sum_{i=1}^N (\tilde{x}'_{i1} \tilde{x}_{i1} + \tilde{x}'_{i2} \tilde{x}_{i2})} \\
&= \frac{\sum_{i=1}^N \frac{\Delta x'_{i2} \Delta y_{i2}}{2}}{\sum_{i=1}^N \frac{\Delta x'_{i2} \Delta x_{i2}}{2}} \\
&= \frac{\sum_{i=1}^N \Delta x'_{i2} \Delta y_{i2}}{\sum_{i=1}^N \Delta x'_{i2} \Delta x_{i2}} \\
&= \hat{\beta}_{FD}
\end{aligned}$$

2. **Solution: b)** Let

$$\begin{aligned}
\hat{u}_{i1} &= \tilde{y}_{i1} - \tilde{x}_{i1} \hat{\beta}_{FE} \\
\hat{u}_{i2} &= \tilde{y}_{i2} - \tilde{x}_{i2} \hat{\beta}_{FE}
\end{aligned}$$

be the fixed effects residuals for two time periods for cross section observation i .

Since $\hat{\beta}_{FE} = \hat{\beta}_{FD}$,

$$\begin{aligned}
\hat{u}_{i1} &= -\frac{\Delta y_{i2}}{2} - \left(-\frac{\Delta x_{i2}}{2}\right) \hat{\beta}_{FD} \\
&= -\left(\frac{\Delta y_{i2}}{2} - \frac{\Delta x_{i2}}{2} \hat{\beta}_{FD}\right) \\
&= -\frac{\hat{e}_i}{2}
\end{aligned}$$

$$\begin{aligned}
\hat{u}_{i2} &= \frac{\Delta y_{i2}}{2} - \frac{\Delta x_{i2}}{2} \hat{\beta}_{FD} \\
&= \frac{\hat{e}_i}{2}
\end{aligned}$$

where $\hat{e}_i$ are the first difference residuals.

Therefore,

$$\sum_{i=1}^N (\hat{u}_{i1} + \hat{u}_{i2}) = \frac{1}{2} \sum_{i=1}^N \hat{e}_i$$

Since $T = 2$:

The FE variance estimate is $\frac{\sum_{i=1}^N (\hat{u}_{i1} + \hat{u}_{i2})}{N-k}$ and the FD variance estimate is $\frac{\sum_{i=1}^N \hat{e}_i}{\frac{1}{2} \frac{i=1}{N-k}}$, thus, $\hat{\sigma}_u^2 = \frac{\hat{\sigma}_e^2}{2}$.

However,

$$\begin{aligned} Var(\hat{\beta}_{FE}) &= \hat{\sigma}_u^2 \left[\sum_{i=1}^N (\tilde{x}'_{i1} \tilde{x}_{i1} + \tilde{x}'_{i2} \tilde{x}_{i2}) \right]^{-1} \\ &= \frac{\hat{\sigma}_e^2}{2} \left[\sum_{i=1}^N \frac{\Delta x'_{i2} \Delta x_{i2}}{2} \right]^{-1} \\ &= \hat{\sigma}_e^2 \left[\sum_{i=1}^N \Delta x'_{i2} \Delta x_{i2} \right]^{-1} \\ &= Var(\hat{\beta}_{FD}). \end{aligned}$$