

Microeconometrics

Linear panel data methods

Alex Armand

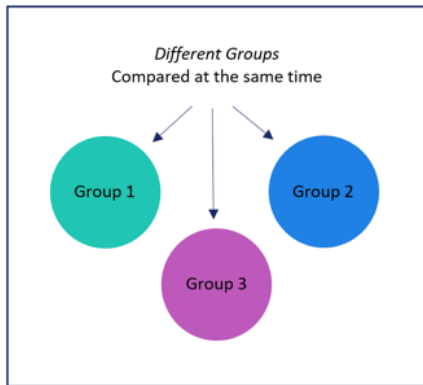
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Summary of today's class

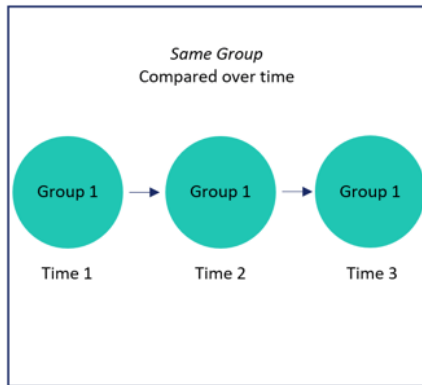
- 1 Panel data setup
- 2 Assumptions needed in panel data models
- 3 Estimation methods and interpretation
 - 1 Pooled OLS (POLS)
 - 2 Fixed Effects (FE)
 - 3 First Differencing (FD)
 - 4 Random Effects (RE)
- 4 Applications

From cross section to panel data

Cross-Sectional Study



Longitudinal Study



Random sampling with panel data

- Random sampling across i with fixed time periods T

$$\{(x_{it}, y_{it}) : t = 1, \dots, T\}$$

- Two cases:

- 1 **Panel is balanced:** each individual i is observed in all periods T
 - We will assume this case for this topic
- 2 **Panel is unbalanced:** don't observe some i for some of the periods t
 - Trickier because we must know why we are missing some time periods for some units
 - Selection models later on in the course

General specification

$$y_{it} = z_i\delta + w_{it}\gamma + g_t\theta + v_{it}$$

- $z_i \Rightarrow$ set of time-constant observed variables
- $w_{it} \Rightarrow$ set of time-varying observed variables
- $g_t \Rightarrow$ vector of aggregate time effects

Common feature: **decomposition of the error term**

$$v_{it} = c_i + u_{it}$$

- 1 $c_i \Rightarrow$ time-invariant unobservable characteristics
- 2 $u_{it} \Rightarrow$ idiosyncratic errors

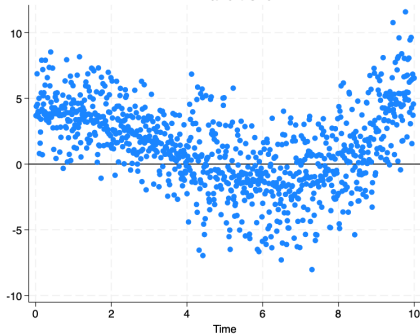
Aggregate time effects

- Time effects remove trends in y_{it} and w_{it} (focus on residual variation)
- How to choose time effects?
 - Depends on how much residual variation you want to use \Rightarrow allow for variation within each time group
- **Example:** assume w_{it} varies daily over 10 years \Rightarrow create some variables capturing time and space
 - $time_t \Rightarrow$ measure the time t continuously (each year is 1 unit)
 - $year_t \Rightarrow$ measure the year of t
 - $d_{j,t} \Rightarrow$ dummy equal to 1 if time t belongs to year j
 - $days_{j,t} \Rightarrow$ dummy equal to 1 if time t belongs to group j in which days are groups of 3 days
 - $reg_i \Rightarrow$ dummy equal to 1 if the region of the respondent is region 1, 0 otherwise

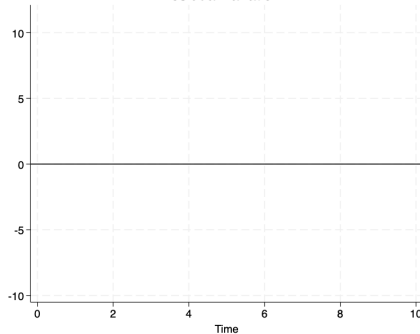
Aggregate time effects – an example

no time effects $\Rightarrow y_{it} = w_{it}\gamma + v_{it}$

A. w and trend



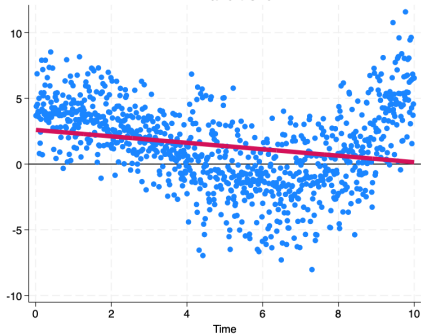
B. Residual variation in w



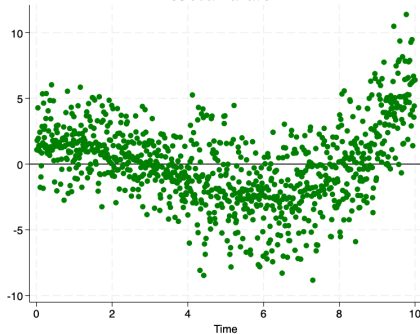
Aggregate time effects – an example

linear trend in time $\Rightarrow y_{it} = w_{it}\gamma + \theta_1 time_t + v_{it}$

A. w and trend



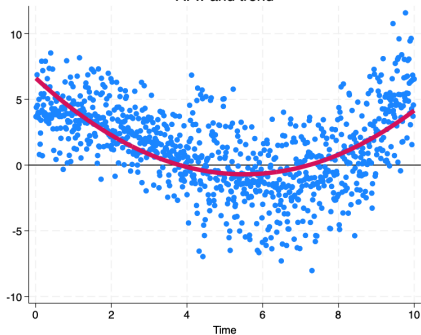
B. Residual variation in w



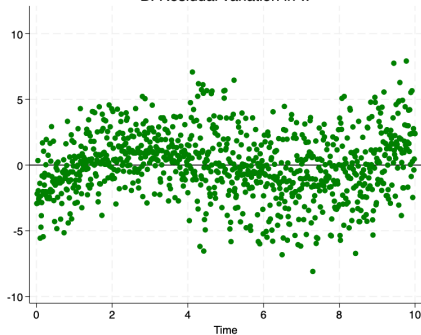
Aggregate time effects – an example

quadratic trend in time $\Rightarrow y_{it} = w_{it}\gamma + \theta_1 time_t + \theta_2 time_t^2 + v_{it}$

A. w and trend



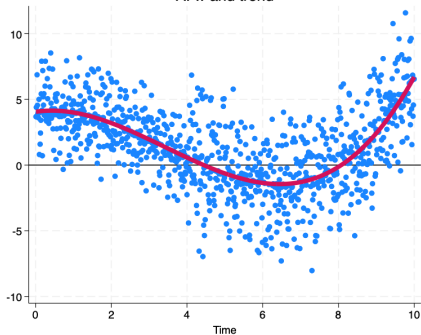
B. Residual variation in w



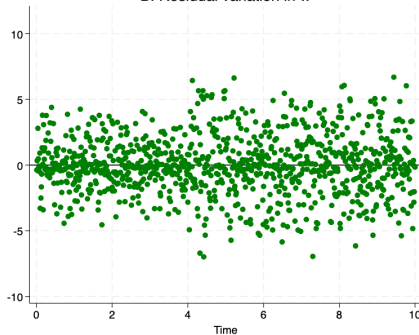
Aggregate time effects – an example

cubic trend in time $\Rightarrow y_{it} = w_{it}\gamma + \theta_1 time_t + \theta_2 time_t^2 + \theta_3 time_t^3 + v_{it}$

A. w and trend



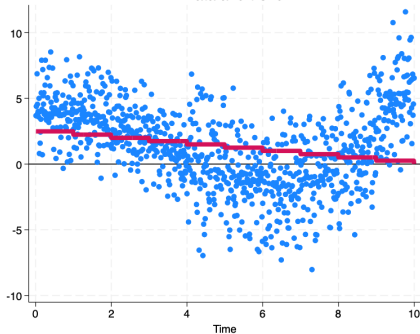
B. Residual variation in w



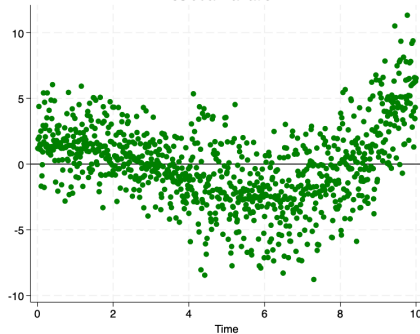
Aggregate time effects – an example

linear trend in year $\Rightarrow y_{it} = w_{it}\gamma + \theta_1 year_t + v_{it}$

A. Data and trend



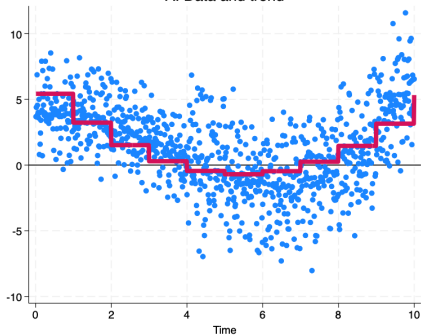
B. Residual variation in w



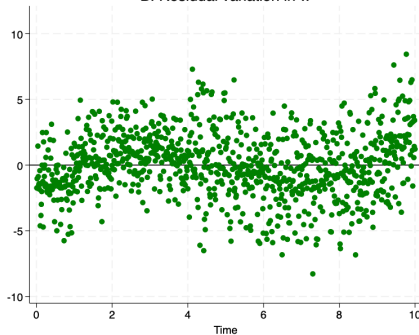
Aggregate time effects – an example

quadratic trend in year $\Rightarrow y_{it} = w_{it}\gamma + \theta_1 \text{year}_t + \theta_2 \text{year}_t^2 + v_{it}$

A. Data and trend



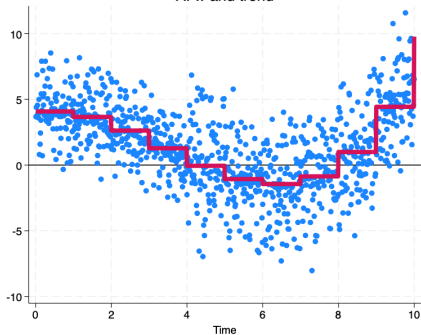
B. Residual variation in w



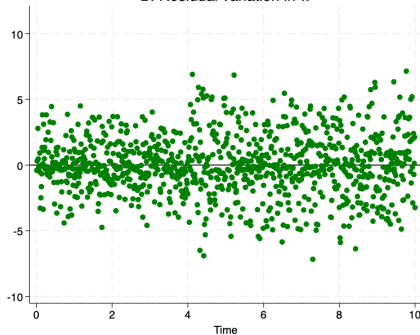
Aggregate time effects – an example

cubic trend in year $\Rightarrow y_{it} = w_{it}\gamma + \theta_1 \text{year}_t + \theta_2 \text{year}_t^2 + \theta_3 \text{year}_t^3 + v_{it}$

A. w and trend



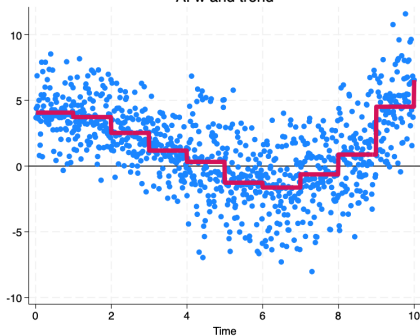
B. Residual variation in w



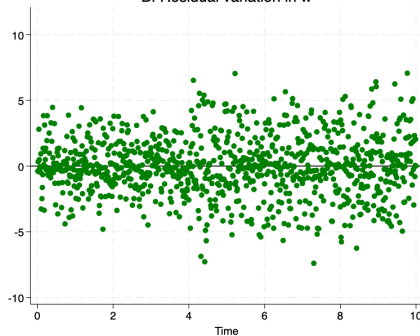
Aggregate time effects – an example

non-linear trend in year \Rightarrow
$$y_{it} = w_{it}\gamma + \sum_{j=2}^{10} \theta_j d_{j,t} + v_{it}$$

A. w and trend



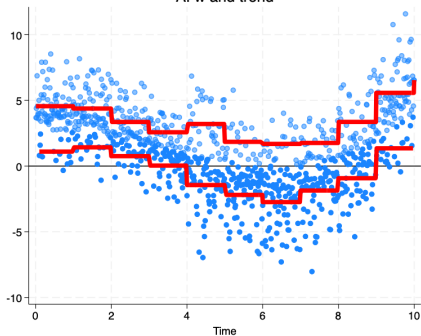
B. Residual variation in w



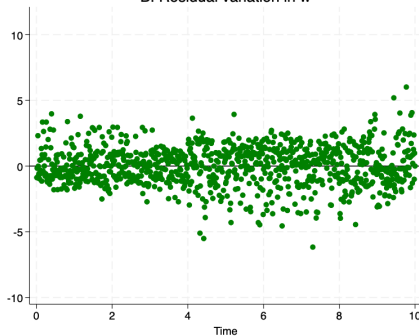
Aggregate time effects – an example

(local) non-linear trend in year $\Rightarrow y_{it} = w_{it}\gamma + \sum_{j=2}^{10} \theta_j d_{j,t} \cdot reg_i + v_{it}$

A. w and trend



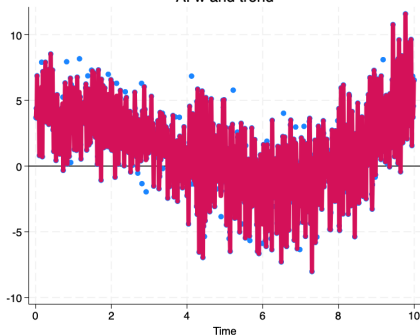
B. Residual variation in w



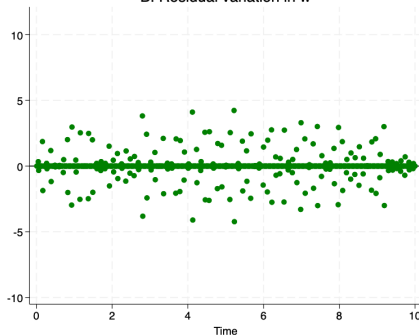
Aggregate time effects – an example

non-linear trend in group of days $\Rightarrow y_{it} = w_{it}\gamma + \sum_{j=2}^{10} \theta_j \text{days}_{j,t} + v_{it}$

A. w and trend



B. Residual variation in w



Consequences of decomposing the error term

- **Correlation structure of the error term:** v_{it} is almost certainly serially correlated

$$\begin{aligned} \text{corr}(v_{i,t}, v_{i,t-1}) &= \text{corr}(c_i + u_{i,t}, c_i + u_{i,t-1}) \\ &= \sigma_c^2 + \text{corr}(c_i, u_{i,t-1}) + \text{corr}(c_i, u_{i,t}) \\ &\quad + \text{corr}(u_{i,t}, u_{i,t-1}) \end{aligned}$$

- We require **two types of assumptions concerning errors:**
 - 1 relationship between covariates and c_i
 - 2 relationship between covariates and u_{it}

Relationship between covariates and c_i

- ① **Fixed effect:** no restrictions on the relationship between c_i and x_{it}
- ② **Random effect:**

$$\text{Cov}(x_{it}, c_i) = 0, \quad t = 1, \dots, T$$

- ③ **Correlated random effects:** we model the relationship between c_i and x_{it}

Relationship between covariates and u_{it}

① Contemporaneous exogeneity

$$E(u_{it} | x_{it}, c_i) = 0$$

② Strict exogeneity

$$E(u_{it} | x_{i1}, \dots, x_{iT}, c_i) = 0$$

③ Sequential exogeneity

$$E(u_{it} | x_{it}, x_{i,t-1}, \dots, x_{i1}, c_i) = 0$$

Estimation

Consider the simple model:

$$y_{it} = x_{it}\beta + v_{it}$$

$$v_{it} = c_i + u_{it}$$

① Pooled OLS (POLS)

② Fixed Effects (FE)

③ First Differencing (FD)

④ Random Effects (RE)

Pooled OLS (POLS)

- Same as OLS but with stacked observations
- Consistency ensured by

① Rank condition

② Orthogonality: $E(x'_{it} v_{it}) = 0$

$$\begin{aligned} E(x'_{it} c_i) &= 0 \\ \text{Contemporaneous exogeneity: } E(x'_{it} u_{it}) &= 0, t = 1, \dots, T \end{aligned}$$

- Decomposition of error term \Rightarrow inference robust to **serial correlation**

Estimation

Consider the simple model:

$$y_{it} = x_{it}\beta + v_{it}$$

$$v_{it} = c_i + u_{it}$$

- 1 Pooled OLS (POLS)
- 2 **Fixed Effects (FE)**
- 3 First Differencing (FD)
- 4 Random Effects (RE)

Fixed Effects (FE)

Obtain **FE estimator** in 2 steps:

- 1 **Between equation** (\bar{y}_i): average the equation across $t \rightarrow$ cross-section

$$\begin{aligned}\bar{y}_i &\equiv \frac{\sum_{t=1}^T y_{it}}{T} = \frac{\sum_{t=1}^T x_{it}\beta + c_i + u_{it}}{T} \\ &= \bar{x}_i\beta + c_i + \bar{u}_i\end{aligned}$$

- 2 **Within equation** (\ddot{y}_{it}): subtract the between equation from the original equation to eliminate c_i

$$\begin{aligned}\ddot{y}_{it} &\equiv (y_{it} - \bar{y}_i) = (x_{it} - \bar{x}_i)\beta + u_{it} - \bar{u}_i \\ &= \ddot{x}_{it}\beta + \ddot{u}_{it}\end{aligned}$$

Fixed Effects (FE)

FE estimator uses pooled OLS for $\ddot{y}_{it} = \ddot{x}_{it}\beta + \ddot{u}_{it}$

$$\hat{\beta}_{FE} = \left(\sum_{i=1}^N \sum_{t=1}^T \ddot{x}_{it}' \ddot{x}_{it} \right)^{-1} \left(\sum_{i=1}^N \sum_{t=1}^T \ddot{x}_{it}' \ddot{y}_{it} \right)$$

Conditions for identification

- ❶ **Orthogonality:** $E(\ddot{x}_{it}' \ddot{u}_{it}) = 0, t=1, \dots, T$
- ❷ **Rank:** $\text{rank } E(\ddot{x}_{it}' \ddot{x}_{it}) = K$
 - Condition is **violated** if x_{it} has elements that:
 - do not vary over time
 - change over time in the same way $\rightarrow \ddot{x}_{it}$ transformation introduces constant terms

FE and orthogonality

- The key condition for consistency is

$$E(\ddot{x}'_{it} \ddot{u}_{it}) = E(\ddot{x}'_{it} u_{it}) = E[(x_{it} - \bar{x}_i)' u_{it}] = 0$$

- The first step is possible because \bar{u}_i is equal to 0
- Includes the following conditions:

$$E(x'_{it} u_{it}) = 0$$

$$E(\bar{x}'_i u_{it}) = E \left[\left(\frac{\sum_{s=1}^T x_{is}}{T} \right)' u_{it} \right] = \frac{\sum_{s=1}^T E(x'_{is} u_{it})}{T} = 0$$

- **Strict exogeneity!**

EXAMPLE: union status and wages

Impact of being in the **union** on **log-wages** using different panels for US

- Two approaches:
 - ① **POLS**: $y_i = \alpha + \gamma \text{union}_i + x_i\beta + v_i$
 - ② **FE**: $y_{it} = \alpha + \gamma \text{union}_{i,t} + x_{it}\beta + c_i + u_{it}$
- Compare estimates – **what do we learn?**

Dataset	Dep. variable: Log-wage	
	POLS	FE
Union status in ...		
May CPS, 1974–75	0.19	0.09
LSYM, 1970–78	0.28	0.19
Michigan PSID, 1970–79	0.23	0.14

Note. Adapted from Freeman (1984), "Longitudinal Analyses of the Effects of Trade Union," *Journal of Labor Economics* Vol. 2, No. 1, pp. 1-26. Estimates are calculated using the surveys listed at left. The cross-section estimates include controls for demographic and human capital variables.

APPLICATION: market concentration and airfares

Measure the impact of market concentration on airfares

- $N = 1,149$ U.S. air routes and the years 1997 through 2000
- y_{it} is $\log(\text{fare}_{it})$ and the key explanatory variable is concen_{it} , the concentration ratio for route i .
- Other covariates are year dummies and the time-constant variables $\log(\text{dist}_i)$ and $[\log(\text{dist}_i)]^2$.
- Note that what we call c_i Stata refers to as u_i .

Dataset

```
. use airfare
```

```
. tab year
```

1997, 1998, 1999, 2000	Freq.	Percent	Cum.
1997	1,149	25.00	25.00
1998	1,149	25.00	50.00
1999	1,149	25.00	75.00
2000	1,149	25.00	100.00
Total	4,596	100.00	

```
. sum fare concen dist
```

Variable	Obs	Mean	Std. Dev.	Min	Max
fare	4596	178.7968	74.88151	37	522
concen	4596	.6101149	.196435	.1605	1
dist	4596	989.745	611.8315	95	2724

POLS estimates (with “wrong” standard errors)

```
. reg lfare concen ldist ldistsq y98 y99 y00
```

Source	SS	df	MS	Number of obs =	4596
Model	355.453858	6	59.2423096	F(6, 4589) =	523.18
Residual	519.640516	4589	.113236112	Prob > F	= 0.0000
				R-squared	= 0.4062
				Adj R-squared	= 0.4054
Total	875.094374	4595	.190444913	Root MSE	= .33651

lfare	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
concen	.3601203	.0300691	11.98	0.000	.3011705	.4190702
ldist	-.9016004	.128273	-7.03	0.000	-1.153077	-.6501235
ldistsq	.1030196	.0097255	10.59	0.000	.0839529	.1220863
y98	.0211244	.0140419	1.50	0.133	-.0064046	.0486533
y99	.0378496	.0140413	2.70	0.007	.010322	.0653772
y00	.09987	.0140432	7.11	0.000	.0723385	.1274015
_cons	6.209258	.4206247	14.76	0.000	5.384631	7.033884

POLS estimates (with serial correlation)

```
. reg lfare concen ldist ldistsq y98 y99 y00, cluster(id)
```

(Std. Err. adjusted for 1149 clusters in id)

		Robust					
lfare		Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	

concen		.3601203	.058556	6.15	0.000	.2452315	.4750092
ldist		-.9016004	.2719464	-3.32	0.001	-1.435168	-.3680328
ldistsq		.1030196	.0201602	5.11	0.000	.0634647	.1425745
y98		.0211244	.0041474	5.09	0.000	.0129871	.0292617
y99		.0378496	.0051795	7.31	0.000	.0276872	.048012
y00		.09987	.0056469	17.69	0.000	.0887906	.1109493
_cons		6.209258	.9117551	6.81	0.000	4.420364	7.998151

FE estimates

```
. xtreg lfare concen ldist ldistsq y98 y99 y00, fe cluster(id)
```

(Std. Err. adjusted for 1149 clusters in id)

			Robust				
lfare		Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	

concen		.168859	.0494587	3.41	0.001	.0718194	.2658985
ldist		(dropped)					
ldistsq		(dropped)					
y98		.0228328	.004163	5.48	0.000	.0146649	.0310007
y99		.0363819	.0051275	7.10	0.000	.0263215	.0464422
y00		.0977717	.0055054	17.76	0.000	.0869698	.1085735
_cons		4.953331	.0296765	166.91	0.000	4.895104	5.011557

sigma_u		.43389176					
sigma_e		.10651186					
rho		.94316439	(fraction of variance due to u_i)				

FE estimates: non-linear effects

- Let the effect of concen depend on route distance.

```
. sum ldist if y00
```

Variable	Obs	Mean	Std. Dev.	Min	Max
-----+-----					
ldist	1149	6.696482	.6595331	4.553877	7.909857

```
. gen ldistconcen = (ldist - 6.7)*concen
```


FE estimates: non-linear effects

```
. xtreg lfare concen ldistconcen y98 y99 y00, fe cluster(id)
```

Fixed-effects (within) regression Number of obs = 4596

Group variable: id Number of groups = 1149

(Std. Err. adjusted for 1149 clusters in id)

		Robust					
lfare		Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	

concen		.1652538	.0482782	3.42	0.001	.0705304	.2599771
ldistconcen		-.2498619	.0828545	-3.02	0.003	-.4124251	-.0872987
y98		.0230874	.0041459	5.57	0.000	.014953	.0312218
y99		.0355923	.0051452	6.92	0.000	.0254972	.0456874
y00		.0975745	.0054655	17.85	0.000	.0868511	.1082979
_cons		4.93797	.0317998	155.28	0.000	4.875578	5.000362

sigma_u		.50598296					
sigma_e		.10605257					
rho		.95791776	(fraction of variance due to u_i)				

From FE to TWFE

Many applications of FE models use **Two Way Fixed Effects (TWFE)**

- Consider this example:

$$y_{it} = \alpha d_{it} + \tau_t + c_i + u_{it}$$

- d_{it} is the time-varying variable of interest
- τ_t and c_i are the time-specific FE and the individual-specific FE
- τ_t and c_i can also be captured by adding indicator variables for each period and individual
 - Replicates FE but with \uparrow computation (many parameters to estimate)

APPLICATION: the costs of low birth weight

How can we identify the **causal impact of low birth weight**?

- Cross-sectional regression would fail orthogonality

$$h_i = \alpha + \beta bw_i + X_i\gamma + \epsilon_i$$

- bw_i is birth weight of child i
- h_i is an indicator of health
- We cannot use **panel data** since you are born only once
- Can we use panel data methods applied to non-panel data?
 - Almond et al. QJE (2005) \Rightarrow effect of birth weight on child health
applying FE estimator to non-panel data – how?

APPLICATION: the costs of low birth weight

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Twins to identify the causal effect (Almond et al. QJE 2005)

- Standard identification problem:

$$(1) \quad h_{ij} = \alpha + bw_{ij}\beta + X_i'\gamma + a_i + \varepsilon_{ij},$$

where h_{ij} is the underlying health of newborn j for mother i , bw_{ij} is birth weight, X_i is a vector of mother-specific observable determinants of health (e.g., race, age, education), a_i reflects mother-specific unobservable determinants of health (e.g., genetic factors), and ε_{ij} represents other newborn-specific idiosyncratic factors, assumed to be independent of all observable and unobservable factors.

- Using twins, we can apply FE to eliminate a_i
 - Time dimension is replaced by the number of siblings \Rightarrow observe multiple birth weight per mother

Comparison of estimates across POLS and FE

OLS is over-estimating the impact on hospital costs – why?

TABLE III

POOLED OLS AND TWINS FIXED EFFECTS ESTIMATES OF THE EFFECT OF BIRTH WEIGHT

Birth weight coefficient	Including congenital anomalies		Excluding congenital anomalies	
	Pooled OLS	Fixed effects	Pooled OLS	Fixed effects
<u>Hospital costs</u>	-29.95	-4.93	—	—
(in 2000 dollars)	(0.84)	(0.44)	—	—
	[-0.506]	[-0.083]	—	—
Adj. R^2	0.256	0.796	—	—
Sample size	44,410	44,410	—	—
<u>Mortality, 1-year</u>	-0.1168	-0.0222	-0.1069	-0.0082
(per 1000 births)	(0.0016)	(0.0016)	(0.0017)	(0.0012)
	[-0.412]	[-0.078]	[-0.377]	[-0.029]
Adj. R^2	0.169	0.585	0.164	0.629
Sample size	189,036	189,036	183,727	183,727

Comparison of estimates across POLS and FE

Similar when looking at dummy variables instead of bw_{ij}

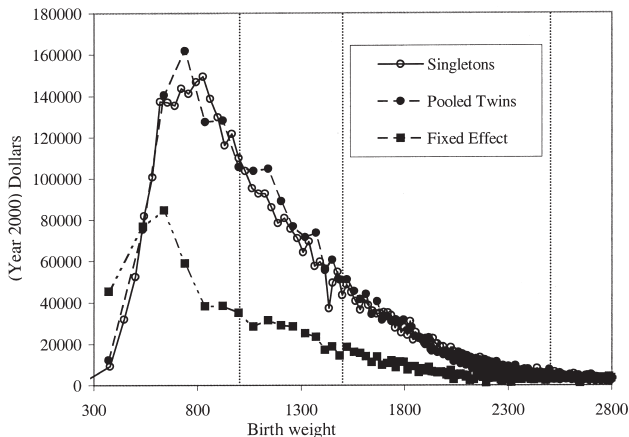


FIGURE Ia

Hospital Costs and Birth Weight

Note: 1995–2000 NY/NJ Hospital Discharge Microdata.

Another TWFE example: difference-in-differences

Example: introduction of a policy restricted to some regions of the country

Time	$t = 0$	$t = 1$
Regions affected	No region	Northern Mexico + Veracruz



Difference-in-Differences (DiD)

A random sample of individuals across the country is observed in two periods $t = 0, 1$

$$y_{it} = \beta + \alpha_i d_{it} + v_{it}$$
$$d_{it} = \begin{cases} 1 & \text{if affected by policy at time } t \\ 0 & \text{otherwise} \end{cases}$$

- DiD estimator applies a standard **TWFE** error decomposition

$$v_{it} = \tau_t + c_i + u_{it}$$

- c_i : unobservable individual fixed effect
- τ_t : aggregate time effect
- u_{it} : idiosyncratic error term

Identification

Compute $E[y_{it}|d_i, t]$ for all groups and for each period $t = 0, 1$

- $E[y_{it}|d_i, t]$ for $d_i = 1$:

$$\begin{cases} \beta + E[c_i|d_i = 1] + \tau_{t_0} + E[u_{it_0}|d_i = 1] & \text{if } t = 0 \\ \beta + E[\alpha_i|d_i = 1] + E[c_i|d_i = 1] + \tau_{t_1} + E[u_{it_1}|d_i = 1] & \text{if } t = 1 \end{cases}$$

- $E[y_{it}|d_i, t]$ for $d_i = 0$:

$$\begin{cases} \beta + E[c_i|d_i = 0] + \tau_{t_0} + E[u_{it_0}|d_i = 0] & \text{if } t = 0 \\ \beta + E[c_i|d_i = 0] + \tau_{t_1} + E[u_{it_1}|d_i = 0] & \text{if } t = 1 \end{cases}$$

Identification

Assumption

Randomization hypothesis holds in first differences:

$$E[v_{it_1} - v_{it_0} | d_i = 1] = E[v_{it_1} - v_{it_0} | d_i = 0] = E[v_{it_1} - v_{it_0}]$$

- $E[y_{it} | d_i, t]$ for $d_i = 1$:

$$\begin{cases} \beta + E[c_i | d_i = 1] + \tau_{t_0} + E[u_{it_0}] & \text{if } t = 0 \\ \beta + E[\alpha_i | d_i = 1] + E[c_i | d_i = 1] + \tau_{t_1} + E[u_{it_1}] & \text{if } t = 1 \end{cases}$$

- $E[y_{it} | d_i, t]$ for $d_i = 0$:

$$\begin{cases} \beta + E[c_i | d_i = 0] + \tau_{t_0} + E[u_{it_0}] & \text{if } t = 0 \\ \beta + E[c_i | d_i = 0] + \tau_{t_1} + E[u_{it_1}] & \text{if } t = 1 \end{cases}$$

Identification: first and second differences

- **1st**: cancels out time-invariant characteristics

$$\begin{aligned}\Delta y_T &= E[y_{it}|d_i = 1, t = 1] - E[y_{it}|d_i = 1, t = 0] \\ &= E[\alpha_i|d_i = 1] + (\tau_{t_1} - \tau_{t_0}) + E[u_{it_1} - u_{it_0}]\end{aligned}$$

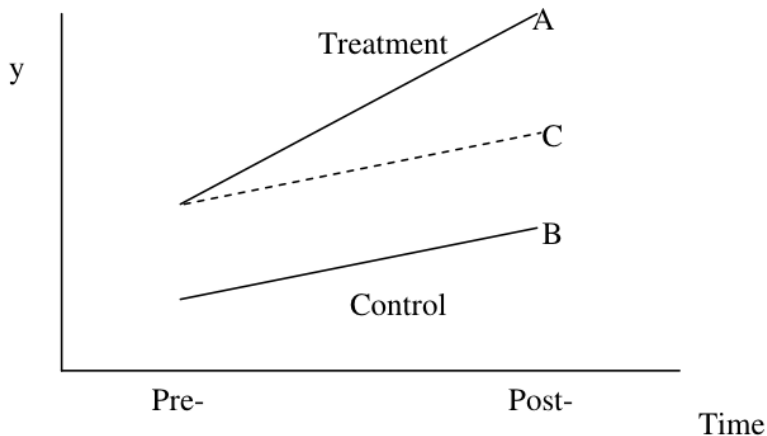
$$\begin{aligned}\Delta y_C &= E[y_{it}|d_i = 0, t = 1] - E[y_{it}|d_i = 0, t = 0] \\ &= (\tau_{t_1} - \tau_{t_0}) + E[u_{it_1} - u_{it_0}]\end{aligned}$$

- **2nd**: cancels out time effects and identifies ATT

$$\Delta y_T - \Delta y_C = E[\alpha_i|d_i = 1] = \alpha^{ATT}$$

What is DiD indentifying?

Excess outcome change for the treated as compared to the non-treated



Estimating DiD

- Use two dummy variables \Rightarrow TWFE
 - 1 **Group identifier** (d_i): 1 if individual i lives in affected regions (independently from time), 0 otherwise
 - 2 **Post** (T_t): 1 if observation refers to $t = 1$, 0 otherwise
- Estimate the following with **OLS**:

$$y_{it} = \alpha_0 + \{\alpha_1 d_i + \alpha_2 T_t + \alpha_3 d_i \cdot T_t\} + X_{it}\beta + v_{it}$$

- $\alpha_1 \Rightarrow$ difference in means across all periods between affected and non-affected regions
- $\alpha_2 \Rightarrow$ difference in means between $t = 0$ and $t = 1$
- $\alpha_3 \Rightarrow$ **DiD estimate**

Violations

- ① **Ashenfelter's dip:** $u_{it_1} - u_{it_0}$ is not unrelated to d

$$E[\alpha^{DiD}] = \alpha^{ATT} + E[u_{it_1} - u_{it_0} | d_{it_1} = 1] + \\ - E[u_{it_1} - u_{it_0} | d_{it_1} = 0]$$

- *Example:* enrolment in a training programme is more likely if a temporary dip in earnings occurs just before the programme

- ② **Lack of common trend:** aggregate time effects are different

$$E[\alpha^{DiD}] = \alpha^{ATT} + (\tau_{1,t_1} - \tau_{1,t_0}) - (\tau_{0,t_1} - \tau_{0,t_0})$$

- ③ **Composition changes:** effects driven by before-after changes in the composition of respondents

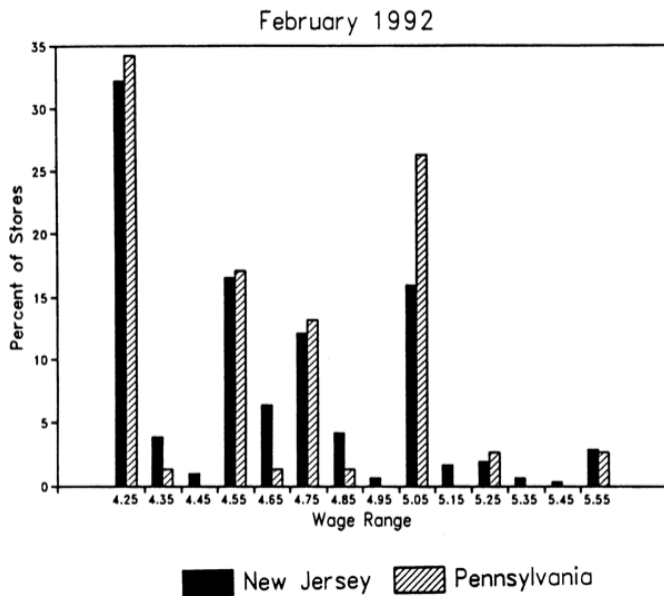
APPLICATION: Card and Krueger (1994)

What is the effect of minimum wage on employment?

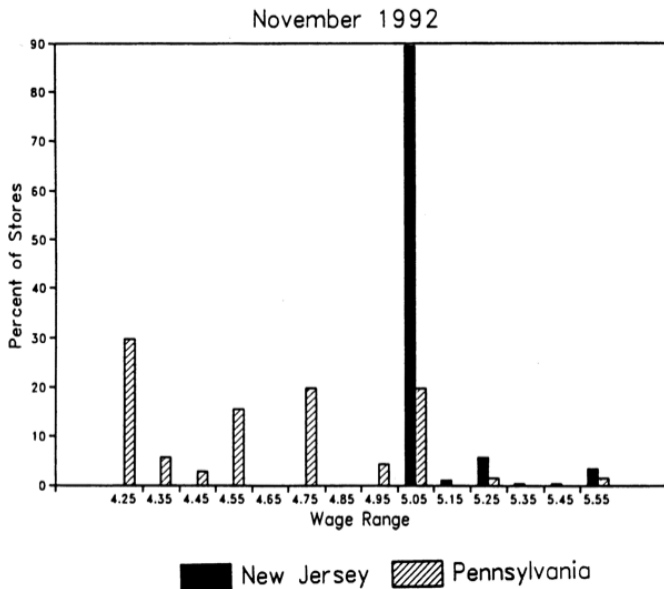
On April 1, 1992, New Jersey's minimum wage rose from \$4.25 to \$5.05 per hour. To evaluate the impact of the law we surveyed 410 fast-food restaurants in New Jersey and eastern Pennsylvania before and after the rise. Comparisons of employment growth at stores in New Jersey and Pennsylvania (where the minimum wage was constant) provide simple estimates of the effect of the higher minimum wage. We also compare employment changes at stores in New Jersey that were initially paying high wages (above \$5) to the changes at lower-wage stores. We find no indication that the rise in the minimum wage reduced employment. (JEL J30, J23)

- Minimum wage change in one state (NJ) between $t = 0$ and $t = 1$
- Compare with neighbouring state (PA) for comparable employment
- Assumptions are valid?

Wage range at $t = 0$ (pre) $t = 1$ (post)



Wage range at $t = 0$ (pre) $t = 1$ (post)



DiD estimates of the effect of minimum wage

- Columns (i) and (ii): 1st differences
- Column (iii): 2nd difference \rightarrow ATT estimate corresponding to α_3 in this OLS regression

$$y_{it} = \alpha_0 + \{\alpha_1 NJ_i + \alpha_2 Post_t + \alpha_3 NJ_i \cdot Post_t\} + X_{it}\beta + v_{it}$$

Outcome measure	Mean change in outcome		
	NJ (i)	PA (ii)	NJ - PA (iii)
<i>Store Characteristics:</i>			
1. Fraction full-time workers ^c (percentage)	2.64 (1.71)	-4.65 (3.80)	7.29 (4.17)
2. Number of hours open per weekday	-0.00 (0.06)	0.11 (0.08)	-0.11 (0.10)
3. Number of cash registers	-0.04 (0.04)	0.13 (0.10)	-0.17 (0.11)
4. Number of cash registers open at 11:00 A.M.	-0.03 (0.05)	-0.20 (0.08)	0.17 (0.10)

TWFE and parallel trends

- Consider 2x2 setting \Rightarrow DiD formula:

$$\alpha^{2 \times 2} = \{E[Y_T|Post] - E[Y_T|Pre]\} - \{E[Y_C|Post] - E[Y_C|Pre]\}$$

- Y_T (group affected) and Y_C (group not affected)
- Rewrite it using **potential outcomes**

$$\begin{aligned} \alpha^{2 \times 2} = & \underbrace{\{E[Y_T^1|Post] - E[Y_T^0|Post]\}}_{\text{ATT}} + \\ & \underbrace{\{E[Y_T^0|Post] - E[Y_T^0|Pre]\} - \{E[Y_C^0|Post] - E[Y_C^0|Pre]\}}_{\text{Non-parallel trends bias (i.e., selection bias)}} \end{aligned}$$

- To cancel out the second term \Rightarrow **parallel trends**

Special case: staggered rollout

Intervention d_{it} is adopted at multiple times t across multiple groups

Time	$t = 0$	$t = 1$	$t = 2$
Regions affected	No region	Northern Mexico + Veracruz	Northern Mexico + Veracruz + Baja California + Pacific Coast



Special case: staggered rollout

- DiD extends to **TWFE** \Rightarrow

$$Y_{it} = \alpha d_{it} + \tau_t + \sigma_i + \epsilon_{it} \quad (1)$$

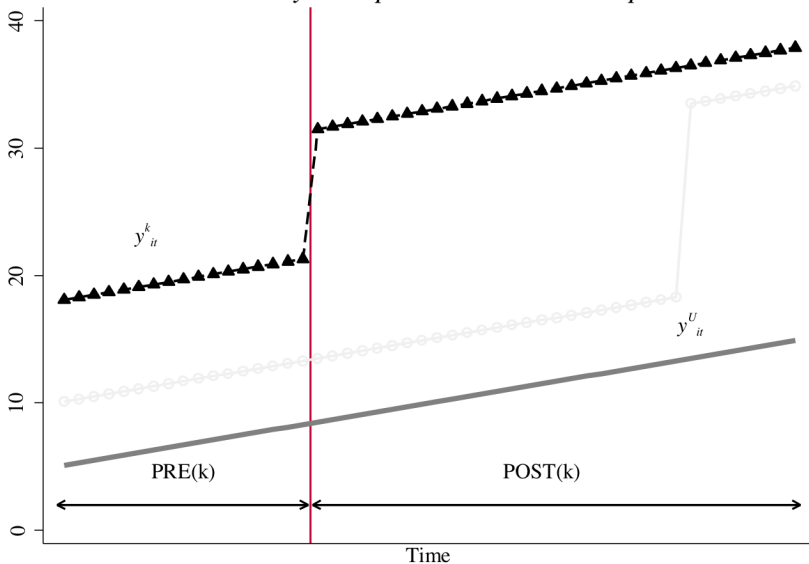
- The design in the example considers three different groups:
 - 1 Regions that are **never affected**: U
 - 2 Regions **affected early**: k
 - 3 Regions **affected later**: l
- Many comparisons are possible – Example: DiD for k and U

$$\delta^{2 \times 2} = [\bar{y}_k^{post(k)} - \bar{y}_k^{pre(k)}] - [\bar{y}_U^{post(k)} - \bar{y}_U^{pre(k)}]$$

- Under what conditions will α equal the ATT?

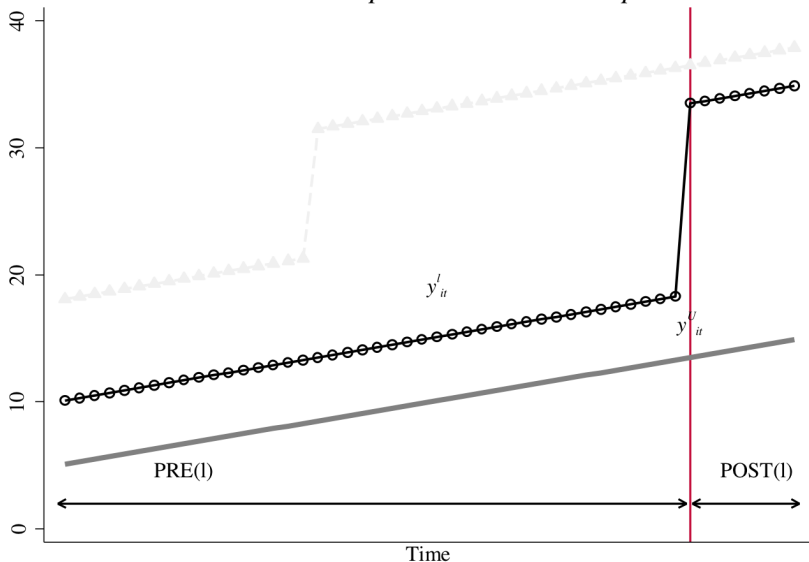
TWFE: early versus never affected

A. Early Group vs. Untreated Group



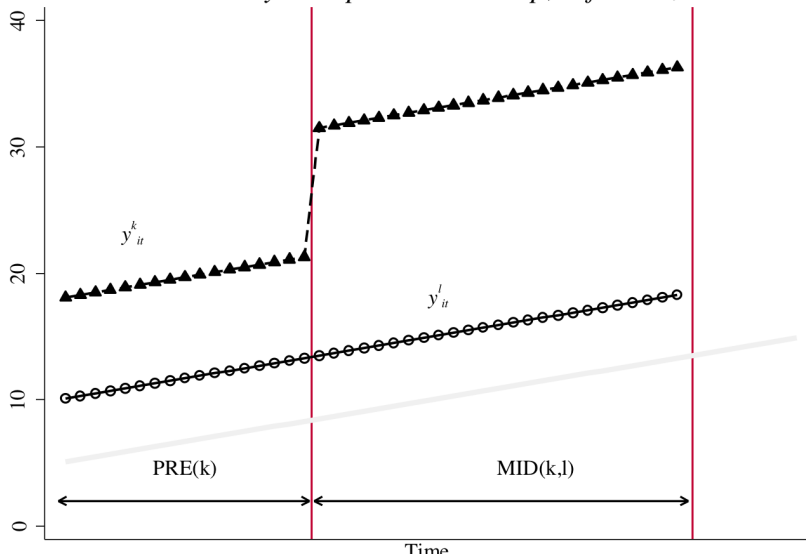
TWFE: late versus never affected

B. Late Group vs. Untreated Group



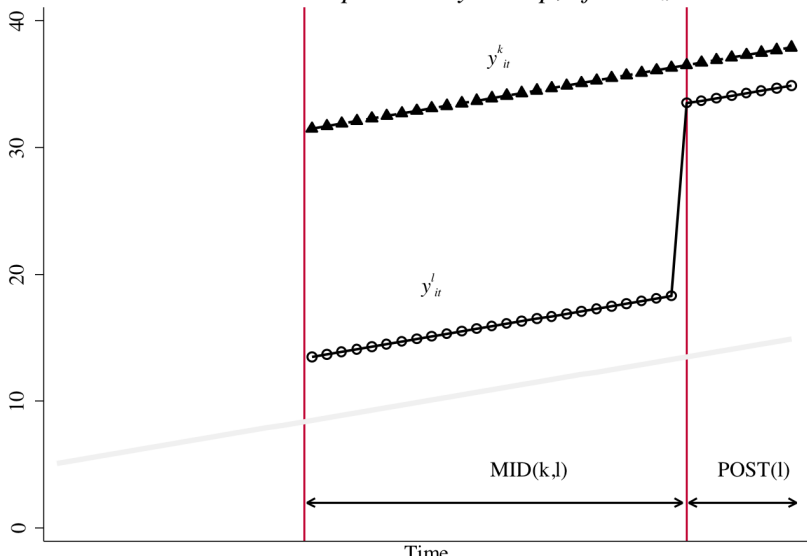
TWFE: early versus late before t^*

*C. Early Group vs. Late Group, before t^*_l*



TWFE: early versus late after t^*

*D. Late Group vs. Early Group, after t_k^**



Goodman-Bacon decomposition

Consider the following 2x2 comparisons:

- $\delta_{kU}^{2 \times 2} \Rightarrow$ affected to never affected
- $\delta_{kl}^{2 \times 2, k} \Rightarrow$ affected early to affected later before t^*
- $\delta_{lk}^{2 \times 2, l} \Rightarrow$ affected early to affected later after t^*

Goodman-Bacon decomposition: α in equation (1) calculates a weighted average of all these 2x2 comparisons

$$\tilde{\delta}^{TWFE} = \sum_{k \neq U} s_{kU} \tilde{\delta}_{kU}^{2 \times 2} + \sum_{k \neq U} \sum_{l > k} s_{kl} \left[\mu_{kl} \delta_{kl}^{2 \times 2, k} + (1 - \mu_{kl}) \delta_{lk}^{2 \times 2, l} \right]$$

- All weights are positive
 - s captures variances
 - μ captures the relevance of comparisons between affected groups

Goodman-Bacon decomposition

- Substitute potential outcomes for all the Y values

$$\delta_{kU}^{2 \times 2} = ATT_k Post + \Delta Y_k^0(Post(k), Pre) - \Delta Y_U^0(Post(k), Pre)$$

$$\delta_{kl}^{2 \times 2} = ATT_k(MID) + \Delta Y_k^0(MID, Pre) - \Delta Y_l^0(MID, Pre)$$

$$\begin{aligned} \delta_{lk}^{2 \times 2} = & ATT_l(Post(l)) + \Delta Y_l^0(Post(l), MID) - \Delta Y_k^0(Post(l), MID) \\ & - (ATT_k(Post) - ATT_k(MID)) \end{aligned}$$

- Key takeaways:
 - All terms are a composition of ATT and **parallel trend biases**
 - $\delta_{lk}^{2 \times 2}$ includes an additional term \Rightarrow **heterogeneity bias**

Interpreting TWFE estimates

The estimator $\tilde{\delta}^{TWFE}$ is the sum of three components:

$$\tilde{\delta}^{TWFE} = VWATT + VWPT - \Delta ATT$$

- ❶ ATT (*VW* stands for variance weighted)
- ❷ Differences in parallel trends
- ❸ Evolution of ATT over time
 - $\Delta ATT = 0$: ATT is constant over time \Rightarrow fine for TWFE
 - $\Delta ATT > 0$: ATT is dynamic and introduces a bias \Rightarrow attenuation bias or even change in sign!

Estimation

Consider the simple model:

$$y_{it} = x_{it}\beta + v_{it}$$

$$v_{it} = c_i + u_{it}$$

- 1 Pooled OLS (POLS)
- 2 Fixed Effects (FE)
- 3 **First Differencing (FD)**
- 4 Random Effects (RE)

First-differencing (FD) estimation

- Removes c_i by **differencing adjacent observations**:

$$\Delta y_{it} = \Delta x_{it}\beta + \Delta u_{it}, \quad t = 2, \dots, T \text{ (we lose } t = 1)$$

- For consistency:

① **Orthogonality**: $E(u_{it}|x_i, c_i) = 0, \quad t = 1, \dots, T$

② **Rank**: $\text{rank } E(\Delta X_i' \Delta X_i) = K$

- FE and FD are the same when $T = 2$

FE estimates

```
. xtreg lfare concen ldist ldistsq y98 y99 y00, fe cluster(id)
```

(Std. Err. adjusted for 1149 clusters in id)

			Robust				
lfare		Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	

concen		.168859	.0494587	3.41	0.001	.0718194	.2658985
ldist		(dropped)					
ldistsq		(dropped)					
y98		.0228328	.004163	5.48	0.000	.0146649	.0310007
y99		.0363819	.0051275	7.10	0.000	.0263215	.0464422
y00		.0977717	.0055054	17.76	0.000	.0869698	.1085735
_cons		4.953331	.0296765	166.91	0.000	4.895104	5.011557

sigma_u		.43389176					
sigma_e		.10651186					
rho		.94316439	(fraction of variance due to u_i)				

FD estimates

```
. reg D.(lfare concen y98 y99 y00), nocons tsscons cluster(id)
```

Linear regression

Number of obs = 3447
F(3, 1148) = 26.29
Prob > F = 0.0000
R-squared = 0.0382
Root MSE = .12508

(Std. Err. adjusted for 1149 clusters in id)

		Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
D.lfare							
concen							
D1.		.1759764	.0430367	4.09	0.000	.0915371	.2604158
y98							
D1.		.0227692	.0041573	5.48	0.000	.0146124	.030926
y99							
D1.		.0364365	.005153	7.07	0.000	.026326	.0465469
y00							
D1.		.0978497	.0055468	17.64	0.000	.0869666	.1087328

- All estimates are similar to FE

Estimation

Consider the simple model:

$$y_{it} = x_{it}\beta + v_{it}$$

$$v_{it} = c_i + u_{it}$$

- ① Pooled OLS (POLS)
- ② Fixed Effects (FE)
- ③ First Differencing (FD)
- ④ **Random Effects (RE)**

Random effects and Generalized Least Squares

Random effects make use of **Generalized Least Squares (GLS)**

- Exploits the correlation structure across multiple equations:
 - ① *unconditional* variances across equations are different
 - ② *unconditional* covariances across equations are non-zero
- **Equations can represent time** \Rightarrow in the population, each period $1, \dots, T$ is one equation

$$y_i = X_i\beta + u_i$$

- y_i is $T \times 1$
- X_i is $T \times K$
- u_i is $T \times 1$

Variance-covariance (VCV) matrix of u_i

Unconditional variance-covariance matrix plays a key role in GLS:

$$W \equiv E(u_i u_i') = \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1G} \\ \sigma_{12} & \sigma_2^2 & \cdots & \sigma_{2G} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1G} & \sigma_{2G} & \cdots & \sigma_G^2 \end{pmatrix}$$

- **Properties:** $W^{-1/2}$ is a symmetric nonsingular matrix such that
 - $W^{-1/2} W^{-1/2} = W^{-1}$
 - $W^{-1/2} W W^{-1/2} = I_G$

GLS transformation and estimator

If W is known, we can multiply y_i by $W^{-1/2}$

$$\begin{aligned}W^{-1/2}y_i &= W^{-1/2}X_i\beta + W^{-1/2}u_i \\ y_i^* &= X_i^*\beta + u_i^*\end{aligned}\tag{2}$$

- Why? \Rightarrow remove correlations in errors

$$E(u_i^*u_i^{*'}) = W^{-1/2}E(u_iu_i')W^{-1/2} = I_G$$

- **GLS estimator** is the POLS estimator of equation (2)

$$\begin{aligned}\beta^{GLS} &= \left(\sum_{i=1}^N X_i^{*'} X_i^* \right)^{-1} \left(\sum_{i=1}^N X_i^{*'} y_i^* \right) \\ &= \left(\sum_{i=1}^N X_i' W^{-1} X_i \right)^{-1} \left(\sum_{i=1}^N X_i' W^{-1} y_i \right)\end{aligned}$$

GLS and assumptions

$$y_i^* = X_i^* \beta + u_i^* \quad (3)$$

- ① Orthogonality: $E(X_i' W^{-1} u_i) = 0$
- ② Rank: $\text{rank } E(X_i' W^{-1} X_i) = K$

If W is not known \Rightarrow feasible GLS procedure

- ① Assume initial $W \Rightarrow$ apply GLS
- ② Use results to estimate $W \Rightarrow$ apply GLS
- ③ Iterate step 2 until GLS estimates are stable

Random Effects

For a random draw i from the population

$$y_{it} = x_{it}\beta + v_{it}$$

$$v_{it} = c_i + u_{it}$$

- Orthogonality

$$E(u_{it}|x_{i1}, x_{i2}, \dots, x_{iT}, c_i) = 0, \quad t = 1, \dots, T$$

$$E(c_i|x_{i1}, x_{i2}, \dots, x_{iT}) = E(c_i)$$

- Rank

- W is nonsingular and $E(X_i' W^{-1} X_i)$ nonsingular.
- non-singularity means in practice that the matrices are invertible.

EXAMPLE: W without serial correlation

- Consider the simplest case:

$$\begin{aligned}\text{Var}(u_{it}) &= \sigma_u^2, \quad t = 1, \dots, T \\ \text{Cov}(u_{it}, u_{is}) &= 0, \quad t \neq s\end{aligned}$$

- From the error decomposition, we can write:

$$\text{Var}(v_{it}) = \text{Var}(c_i + u_{it}) = \sigma_c^2 + \sigma_u^2$$

$$\begin{aligned}\text{Cov}(v_{it}, v_{is}) &= \text{Cov}(c_i + u_{it}, c_i + u_{is}) \\ &= \text{Var}(c_i) + \text{Cov}(c_i, u_{is}) + \text{Cov}(u_{it}, c_i) + \text{Cov}(u_{it}, u_{is}) \\ &= \sigma_c^2\end{aligned}$$

EXAMPLE: W without serial correlation

- The matrix W can be written as:

$$W = \begin{pmatrix} \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & \sigma_c^2 & \cdots & \sigma_c^2 \\ \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & \cdots & \vdots \\ \vdots & \ddots & \ddots & \vdots & \sigma_c^2 \\ \sigma_c^2 & \cdots & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 \\ \sigma_c^2 & \cdots & \sigma_c^2 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 \end{pmatrix}$$

- FGLS requires the initial $W \Rightarrow$ only 2 parameters
 - 1 σ_u^2
 - 2 σ_c^2

Estimator of σ_u^2 and σ_c^2

Starting point \Rightarrow POLS \Rightarrow use residuals v_{it} to estimate both

① How to estimate σ_u^2 ?

- Since $v_{it} - \bar{v}_i = u_{it} - \bar{u}_i$, we can write:

$$\begin{aligned} \text{Var}(v_{it} - \bar{v}_i) &= \text{Var}(u_{it} - \bar{u}_i) = \sigma_u^2 + \frac{\sigma_u^2}{T} - 2\text{Cov}(u_{it}, \bar{u}_i) \\ &= \sigma_u^2 + \frac{\sigma_u^2}{T} - 2\frac{\sigma_u^2}{T} \\ &= \sigma_u^2 \frac{T-1}{T} \\ \frac{T}{T-1} \text{Var}(v_{it} - \bar{v}_i) &= \sigma_u^2 \end{aligned}$$

② How to estimate σ_c^2 ?

- Easy to compute because $\text{Cov}(v_{it}, v_{is}) = \sigma_c^2$ (see previous slide)
- **Breusch-Pagan test**: test whether $H_0 : \sigma_c^2 = 0$

RE estimator

- 1 Use initial \hat{W}
- 2 Apply FGLS estimator as RE estimator:

$$\widehat{Avar}(\hat{\beta}_{RE}) = \left(\sum_{i=1}^N \mathbf{X}_i' \hat{W}^{-1} \mathbf{X}_i \right)^{-1} \left(\sum_{i=1}^N \mathbf{X}_i' \hat{W}^{-1} \hat{v}_i \hat{v}_i' \hat{W}^{-1} \mathbf{X}_i \right) \left(\sum_{i=1}^N \mathbf{X}_i' \hat{W}^{-1} \mathbf{X}_i \right)^{-1}$$

- 3 Use new residuals to compute a new estimate of W
- 4 Repeat steps 2–3 until convergence

Application: market concentration and airfares

- $N = 1,149$ U.S. air routes and the years 1997 through 2000
- $y_{it} \Rightarrow \log(\text{fare}_{it})$
- key explanatory variable $\Rightarrow \text{concen}_{it}$ (concentration ratio for route i)

```
. use airfare
```

```
. tab year
```

1997, 1998, 1999, 2000	Freq.	Percent	Cum.
-----+			
1997	1,149	25.00	25.00
1998	1,149	25.00	50.00
1999	1,149	25.00	75.00
2000	1,149	25.00	100.00
-----+			
Total	4,596	100.00	

```
. sum fare concn dist
```

Variable	Obs	Mean	Std. Dev.	Min	Max
-----+					
fare	4596	178.7968	74.88151	37	522
concn	4596	.6101149	.196435	.1605	1
dist	4596	989.745	611.8315	95	2724

POLS estimates

```
. reg lfare concen ldist ldistsq y98 y99 y00, cluster(id)
```

(Std. Err. adjusted for 1149 clusters in id)

		Robust					
lfare		Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
-----+-----							
concen		.3601203	.058556	6.15	0.000	.2452315	.4750092
ldist		-.9016004	.2719464	-3.32	0.001	-1.435168	-.3680328
ldistsq		.1030196	.0201602	5.11	0.000	.0634647	.1425745
y98		.0211244	.0041474	5.09	0.000	.0129871	.0292617
y99		.0378496	.0051795	7.31	0.000	.0276872	.048012
y00		.09987	.0056469	17.69	0.000	.0887906	.1109493
_cons		6.209258	.9117551	6.81	0.000	4.420364	7.998151

FE estimates

```
. xtreg lfare concen ldist ldistsq y98 y99 y00, fe cluster(id)
```

(Std. Err. adjusted for 1149 clusters in id)

			Robust				
lfare		Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	

concen		.168859	.0494587	3.41	0.001	.0718194	.2658985
ldist		(dropped)					
ldistsq		(dropped)					
y98		.0228328	.004163	5.48	0.000	.0146649	.0310007
y99		.0363819	.0051275	7.10	0.000	.0263215	.0464422
y00		.0977717	.0055054	17.76	0.000	.0869698	.1085735
_cons		4.953331	.0296765	166.91	0.000	4.895104	5.011557

sigma_u		.43389176					
sigma_e		.10651186					
rho		.94316439	(fraction of variance due to u_i)				

Note that what we call c_i Stata refers to as u_i .

RE estimates

```
. xtreg lfare concen ldist ldistsq y98 y99 y00, re cluster(id)
```

(Std. Err. adjusted for 1149 clusters in id)

lfare	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
concen	.2089935	.0422459	4.95	0.000	.126193	.2917939
ldist	-.8520921	.2720902	-3.13	0.002	-1.385379	-.3188051
ldistsq	.0974604	.0201417	4.84	0.000	.0579833	.1369375
y98	.0224743	.0041461	5.42	0.000	.014348	.0306005
y99	.0366898	.0051318	7.15	0.000	.0266317	.046748
y00	.098212	.0055241	17.78	0.000	.0873849	.109039
_cons	6.222005	.9144067	6.80	0.000	4.429801	8.014209
sigma_u	.31933841					
sigma_e	.10651186					
rho	.89988885	(fraction of variance due to u_i)				

- Notice that the RE and POLS coefficients on the time-constant distance variables are pretty similar, something that often occurs.

RE estimates: omitting distance

```
. xtreg lfare concen y98 y99 y00, re cluster(id)
```

Random-effects GLS regression	Number of obs	=	4596
Group variable: id	Number of groups	=	1149

(Std. Err. adjusted for 1149 clusters in id)

	lfare	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
concen		.0468181	.0427562	1.09	0.274	-.0369826	.1306188
y98		.0239229	.0041907	5.71	0.000	.0157093	.0321364
y99		.0354453	.0051678	6.86	0.000	.0253167	.045574
y00		.0964328	.0055197	17.47	0.000	.0856144	.1072511
_cons		5.028086	.0285248	176.27	0.000	4.972178	5.083993
sigma_u		.40942871					
sigma_e		.10651186					
rho		.93661309	(fraction of variance due to u_i)				

- Estimate is much smaller than FE estimate
 - Can be very **harmful to omit time-constant variables in RE**